

1 AP20 Rec'd PCT 24 MAY 2006

TWIN CHUCK DRILL WITH ONE DRIVE SHAFT**Field of the Invention**

THIS INVENTION relates to a pistol-grip tool having two chucks that are interchangeable in position, and is more specifically concerned with such a tool capable
5 of being controlled by one hand of a user so that his other hand is freed for some other purpose.

State of the Art

The use of a tool such as an electric drill, at an overhead position presents special problems. When drilling a hole it is often necessary to first form a pilot hole and then
10 enlarge it with a second drill of larger diameter. If the user is standing on a ladder to form the pilot hole, it is necessary for him to descend the ladder if using a single chuck drill, and then replace the drill bit with one of larger size. The user must then ascend the ladder once again to find the pilot hole to be enlarged. If the pilot hole is not sufficiently deep for the larger drill, the whole process must be repeated.

15 The need for a tool having two chucks that are interchangeable in position has long been recognized and is the subject of a number of patented proposals. However these proposals have either resulted in a tool that is impracticable to use or which does not allow the user to interchange the positions of the chucks without using both hands. Thus the advantage of having one hand free for some other purpose, such as to hold a
20 ladder the user may be standing on, is lost.

Object of the Invention

An object of this invention is to provide an improved two-chuck drill.

The Invention

In accordance with the present invention a pistol-grip tool has first and second chucks
25 one of which may be replaced by the other at a common driving position; a rotary drive

shaft providing drive to whichever of the chucks is at the common driving position; a releasable device such as a clutch operable to disconnect the rotary drive shaft from the chuck at the driving position when the chucks are to be interchanged; a chuck-changing unit operable with drive obtained from the drill motor after the device has been released, to re-position the chuck formerly in use to one side of the common driving position and then to turn it about the drive shaft axis to occupy a position in front of the pistol-grip, the unit also bringing the second chuck from a position in front of the pistol-grip to the common driving position; and, a mechanism operable by the same hand of the tool user as is holding the pistol-grip, to initiate operation of the chuck-changing unit and the engagement and disengagement of the device so that the drive from the drive shaft is only imparted to the chuck at the driving position when the other chuck occupies a position in front of the pistol-grip of the tool. The device preferably comprises a spline engaging a socket in a chuck when power is to be transmitted from the drive shaft to whichever of the chucks is at the common driving position.

15 Advantage of the Invention

An advantage of the tool of the invention is that the chuck not in use always occupies a position in front of the pistol-grip where it is stationary and allows normal operation of the tool. When it is required to interchange the positions of the chucks this may be carried out, for example, by the user depressing a second trigger on the pistol grip while the tool is not working. This can be arranged to initiate a control sequence that interchanges the positions of the chucks, and then restores the driving connection between the drive shaft and the chuck at the common driving position. Preferably, the tool cannot transmit power from the drive shaft to either of the chucks until the chuck-interchange sequence has been completed.

25 Introduction to the Drawings

The invention will now be described in more detail, by way of example, with reference to the accompanying largely diagrammatic drawings; in which:

In the Drawings

FIGURES 1 to 18 are respectively partially exploded and simplified views of parts of a front end-portion of a pistol-grip drill, taken from different directions and which show successive stages during change-over of two chucks, the figures showing positions
5 occupied by the drill parts during two successive chuck change-over sequences.

Description of Preferred Embodiment

In the figures, corresponding parts of the drill have the same reference numbers.

The drill front end shown generally at 1 includes the forward portion of a drill casing 2 containing an electric motor (not shown) controlled by a trigger switch 3 mounted on a
10 pistol-grip 4 that is gripped by one hand of a user when the drill is in use.

The motor rotates a drill drive shaft 5 that can be reciprocated between two axially displaced positions, shown respectively in Figures 1 and 2, by a solenoid mechanism in a cylindrical box 6 surrounding the shaft 5. An arrow 7 shows the direction of rotation of the shaft 5.

15 The casing 2 has a forward extension 8 that can be rotated about the axis of the shaft 5 and also turned through ninety degrees in the same plane as the axis of the shaft. The shaft 5 carries a cylindrical gear 10 that reciprocates with the shaft and is rotated by it. The gear 10 has a ring of parallel teeth having tapered ends to assist their meshing with the teeth of a circular toothed track 12 extending around one side of a disc 13. In
20 practice only one quarter of the length of track is used. The track teeth also have tapered ends to assist their meshing with the gear 10. The disc 13 is pivotally mounted on a spindle 14 extending between the extension 8 and a collar 15 through which the shaft 5 is a close sliding fit. Opposite ends of the used section of the track 12 are respectively provided with stops 16 and 17 that limit the angle to which the gear 10 can
25 travel around the track 12 when the shaft 5 is rotated.

As explained above, the connection between the casing 2 and the extension 8 allows the extension 8 two freedoms of movement. One freedom of movement comprises a rotational movement of the extension 8 through 180° about the axis of the shaft 5 as shown in successive figures 4 to 8, and the second freedom of movement allows the
5 extension 8 to rotate through ninety degrees about the axis of pivot 14 as shown in successive figures 2 to 4.

The casing 8 carries two rotatable drill drive chucks 20 and 21 that project at right angles to one another, as shown in figure 1. The chuck 20 is shown in the driving position of the drill and is illustrated supporting a conventional removable drill bit 23.
10 The other chuck 21 is illustrated supporting a counter-sinking bit 24 at a position at which it extends downwardly forwardly of the pistol-grip 4 of the drill.

In the position of the drive shaft 5 illustrated in figure 1, the gear 10 is positioned forwardly of the track 12 so that the gear and track are not in mesh. However, if the mechanism in the box 6 is operated, the shaft 5 is retracted to the right of figure 1
15 bringing the teeth of the gear 10 into mesh with the teeth of the track 12. To establish a driving connection to the chuck in use, the forward end of the shaft 5 is of hexagonal cross-section and fits within a socket of complementary cross-section of whichever of the chucks 20, 21 is in the driving position at the left-hand end of the drive shaft.

Operation of the Preferred Embodiment

20 The operation of the chuck-changing mechanism shown in the drawings will now be described.

With the parts of the drill in the positions shown in figure 1, the trigger 3 can be squeezed so that the drive from the drill motor is transmitted through the shaft 5 to rotate the drill bit 23 in order to make a drill hole. When a drill hole of the appropriate
25 depth has been formed, its mouth can be countersunk by bringing the chuck 21 and the countersinking bit 24 to the drive position in place of the drill bit 23. This is achieved by squeezing a second trigger 9 positioned above the trigger 3. It should be noted that

the user of the drill can squeeze the second trigger 9 with the same hand as is holding the pistol-grip and operating the first trigger 3.

The action of pressing the trigger 9 is to energise a sequencing circuit that carries out the following steps: The drill drive motor is first temporarily de-energised and the mechanism in the box 6 is operated against the resilient bias of a spring (not shown) to
5 withdraw the forward end-portion of the shaft 5 from the socket in the chuck 20. Simultaneously the gear 10 is brought into mesh with the teeth of the used section of the rack 12. This is shown in figure 2. The user maintains the trigger 9 depressed and the sequencing circuit then re-energises the driving motor so that the gear 10 is rotated to
10 drive the disc 13 in its own plane in a clockwise direction by way of the meshing gear 10 and rack 12. This displaces the two chucks 20,21 angularly so that the chuck 21 moves towards the driving position formerly occupied by chuck 20 and the chuck 20 moves towards a vertically upward position. Successive stages in this movement are shown in figures 3 and 4. When the chuck 20 reaches the position shown in figure 4,
15 the gear 10 abuts the stop 16 so that further rotation of the disc 13 about the axis of the spindle 14 is prevented. One freedom of movement of the extension 8 has then been completed.

As the gear 10 cannot rotate further along the track 12, further rotation of the drive shaft 5 causes the extension 8 and disc 13 to and rotate bodily around the axis of the drive
20 shaft 5. This moves the chuck 20 from the position shown in figure 4 through the successive positions shown in figures 5, 6 and 7 to the position shown in figure 8 at which the chuck 20 is positioned directly in front of the pistol-grip 4. During this rotation of the chuck 20 the second chuck 21 remains in the driving position of the drill as shown. Once the chuck 20 has reached the position shown in figures 8 and 9, a
25 mechanical switch (not shown) is operated by the extension 8 to stop operation of the mechanism in the box 6 and de-energise the drill drive motor. The spring associated with the mechanism in the box 6 then advances the front-end of the drive shaft 5 towards the front of the drill. This forward movement of the drive shaft 5 disengages the pinion 10 from the rack 12 (as shown in figure 10), and the forward end of the drive
30 shaft 5 then enters the socket in the back of the chuck 21 to establish a driving

engagement between the drill motor drive shaft 5 and the chuck 21. On completion of this movement of the shaft 5, the forward movement of the drive shaft 5 operates a switch (not shown) to allow the operation of the trigger 3 to energise the drive motor once again and enable the countersinking bit in the chuck 21 to be used.

- 5 If it is again required to interchange the positions of the chucks 20 and 21, the above procedure is repeated as shown in the sequence of figures 11 to 18. The mechanism in the box 6 is operated to withdraw the drill shaft 5 from the chuck 21 against the force of the resilient spring bias, and to temporarily de-energise the electrical circuit to prevent operation of the drill motor from the trigger 3. As shown in figure 11 the withdrawal
10 movement of the shaft 5 brings the gear 10 into mesh once again with the teeth of the arcuate rack 12 as shown in figure 11. When the trigger 9 is now squeezed, the electrical circuit to the motor is again energised by the sequencing circuit but in a way which reverses its direction of rotation. The shaft 5 is now rotated in the direction indicated by the arrow in figure 12, to rotate the disc 13 in a counterclockwise direction,
15 as shown in figure 12, about the axis of the spindle 14.

- The counterclockwise movement of the disc 13 moves the chuck 21 upwardly and brings the chuck 20 into alignment with the drive shaft 5, as shown in figure 13. This movement is completed when the rack 12 has turned through ninety degrees and the gear 10 abuts the stop 17 at the end of the track 12. When this occurs, further rotation
20 of the track 12 is prevented and the turning movement of the shaft 5 is imparted to turn the disc 13 and extension 8 bodily about the axis of the shaft 5. This brings the chuck 21 from a vertically upwards position shown in figure 13, through the stages shown in figures 14, 15 and 16, to the vertically downwards position shown in figure 17 when it is located a short distance in front of the pistol-grip 4. This movement is terminated by
25 the actuation of a switch (not shown) responsive to movement of the extension 8. The mechanism in the box 6 is de-energised by the switch to allow the resilient spring bias on the shaft 5 to move the shaft 5 axially in a forward direction to bring its free end-portion into engagement with the socket at the back of the chuck 20. Simultaneously the gear 10 is disengaged from the rack 12 and the parts of the drill assume the positions
30 shown in figure 18. The trigger 9, which initiated the interchange of the two chucks 20

and 21, is then released automatically by the forward movement of the shaft 5 to allow the drill to be again operated by squeezing the trigger 3.

Modification of Preferred Embodiment

In a modification (not shown) of the above-described arrangement, the extension 8 carries two opposed spaced parallel tracks 12 which share a common axis of rotation and respectively mesh with the teeth of the gear 10 on its opposite sides. The gear 10 is thus trapped between the two tracks so that a dynamically strong arrangement results in which the risk of the teeth of the gear 10 being forced out of engagement with the teeth of the tracks 12 when under load, is greatly reduced. The additional track 12 used in this modification turns freely about the axis of the spindle 14 and thus is simply an idler and does not participate in the transmission of drive between the shaft 5 and the chuck at the driving position in front of the casing 12.

CLAIMS:

1. A pistol-grip tool having first and second chucks one of which may be replaced by the other at a common driving position; a releasable device such as a clutch operable to disconnect the rotary drive shaft from the chuck at the driving position when the
5 chucks are to be interchanged; a chuck-changing unit operable with drive obtained from the drill motor, after the device has been released, to re-position and then to turn it about the drive shaft axis to occupy a position in front of the pistol-grip bringing the second chuck from a position in front of the pistol-grip to the common driving position; and a mechanism operable by the same hand of the tool user as is holding the pistol-
10 grip, to initiate operation of the chuck-changing unit and the disengagement and re-engagement of the device so that the drive from the drive shaft is only imparted to the chuck at the driving position when the other chuck is occupying a position in front of the pistol-grip of the tool.
2. A tool as set forth in claim 1, including a finger button alongside the pistol-grip
15 which can only operate the device when the drive shaft is not rotating.
3. A tool as set forth in claim 1 or claim 2, having a part which carries the chucks and which has two degrees of freedom so that it is bodily rotatable about the drive shaft and is also rotatable in its own plane.
4. A tool as set forth in claim 3, in which said part carries a rotatable disc having
20 an arcuate section of a toothed track, of a and the device comprises a gear through which the drive shaft is slidable without relative rotation and which is displaceable into and out of mesh with the arcuate section of the track by reciprocation of the drive shaft.

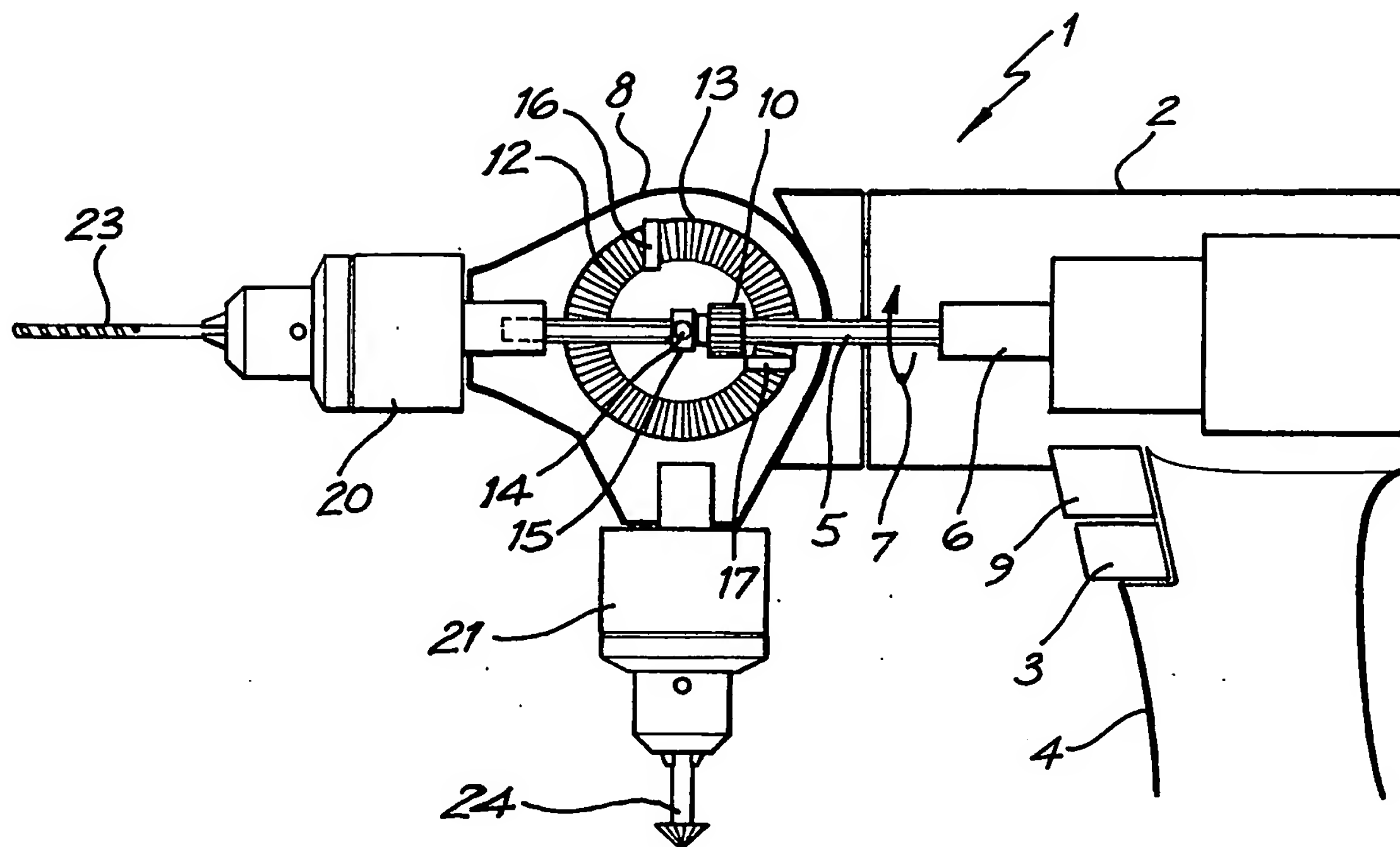


FIG. 1

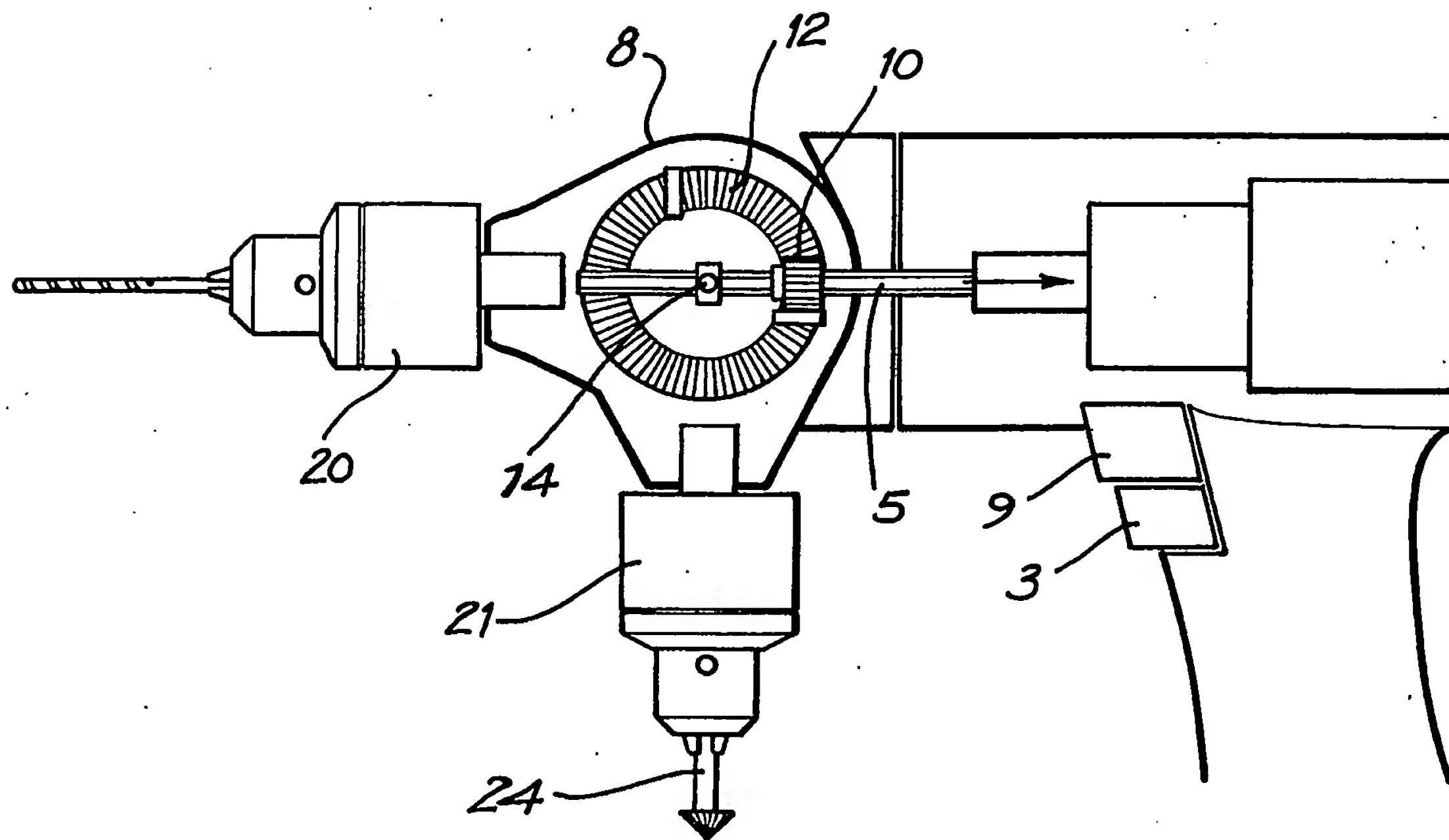


FIG. 2

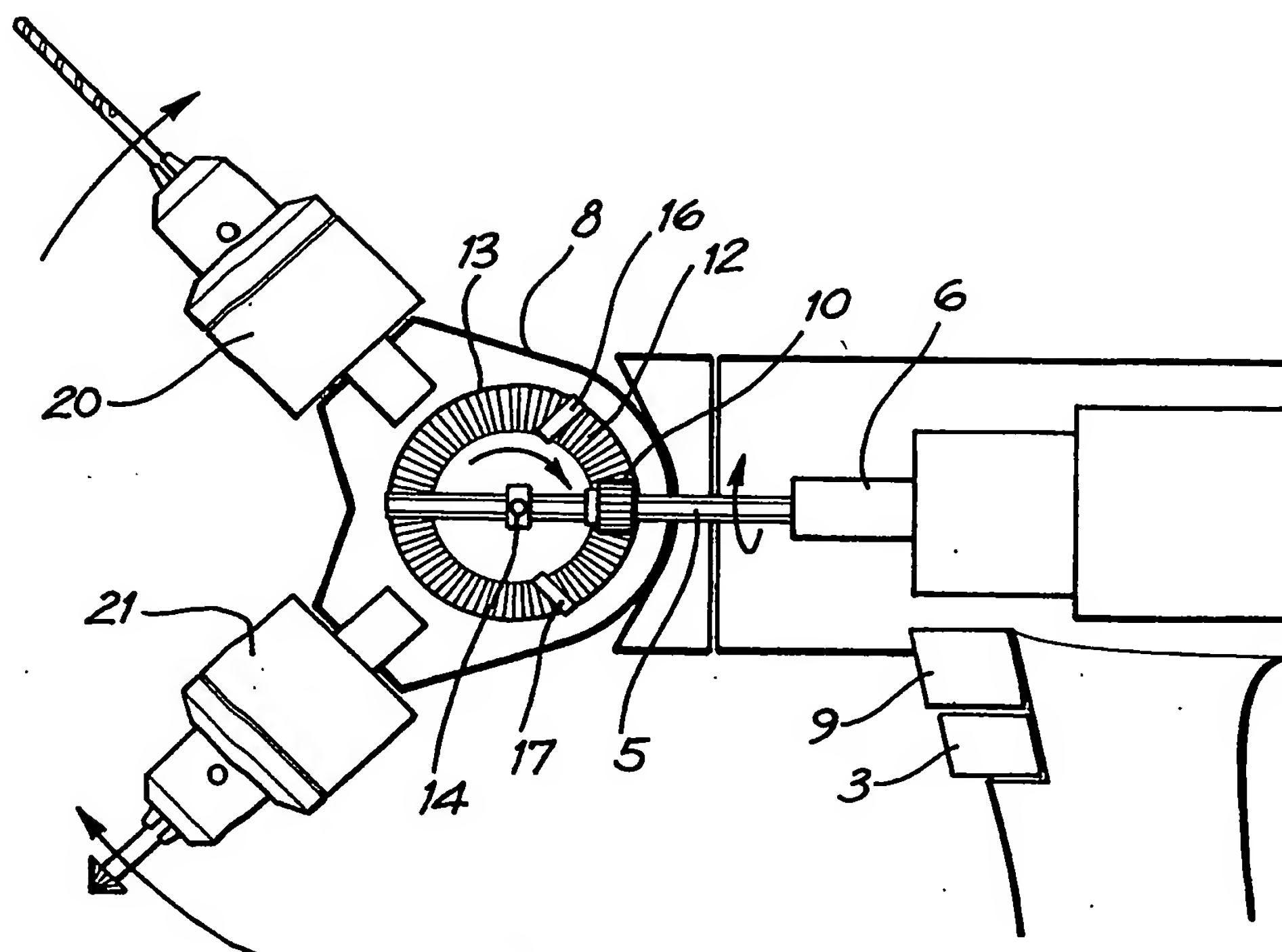


FIG. 3

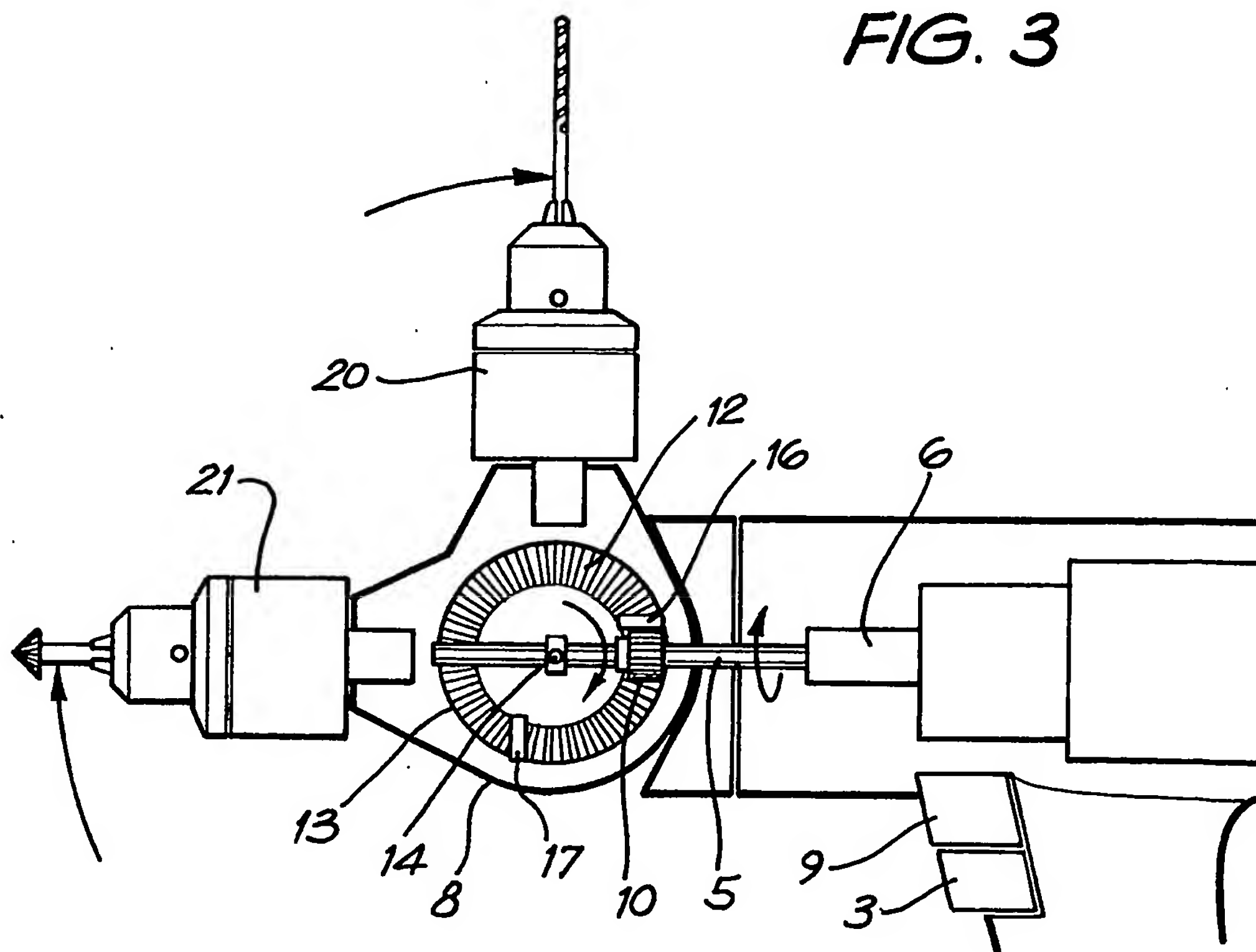


FIG. 4

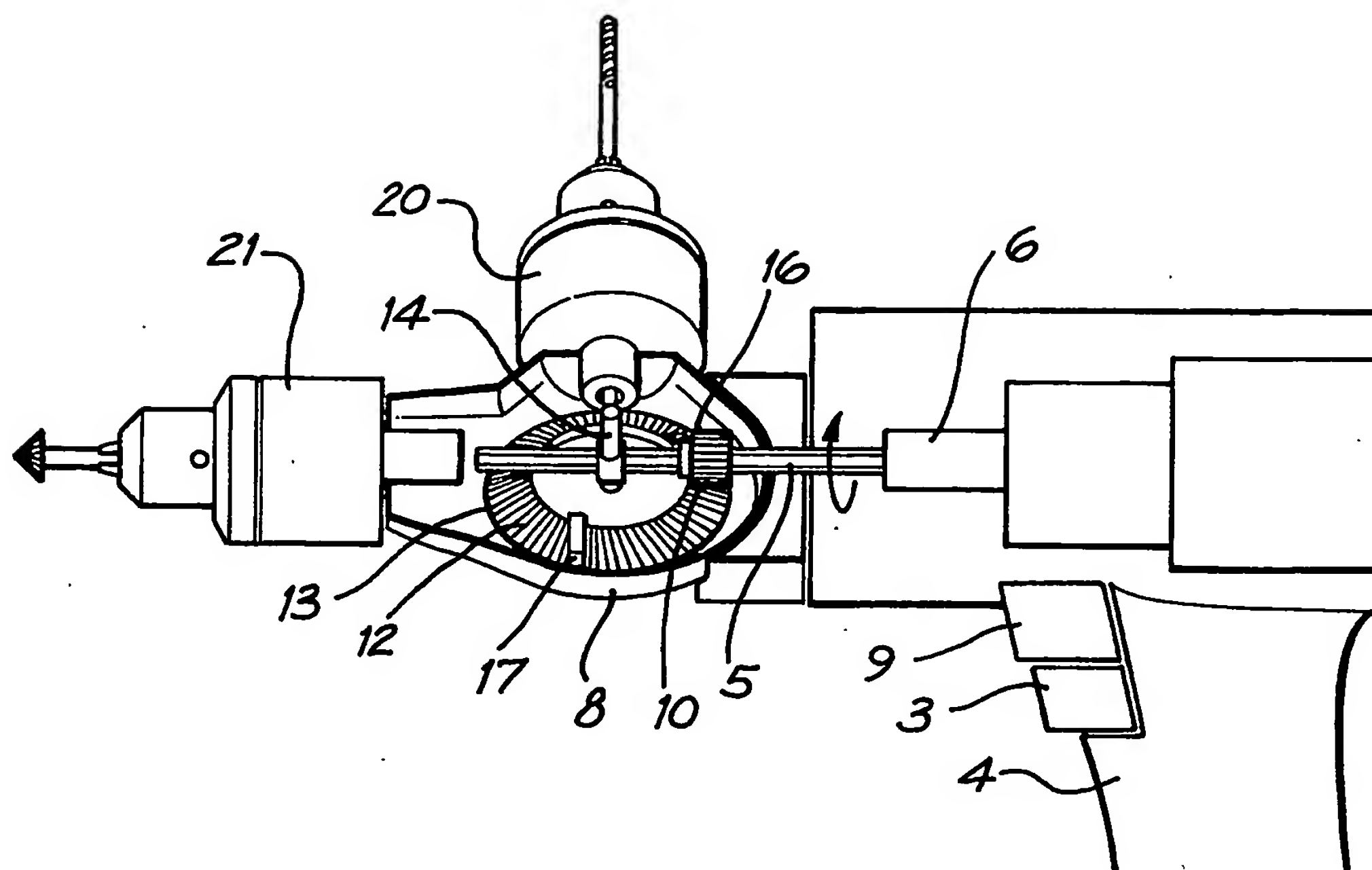


FIG. 5

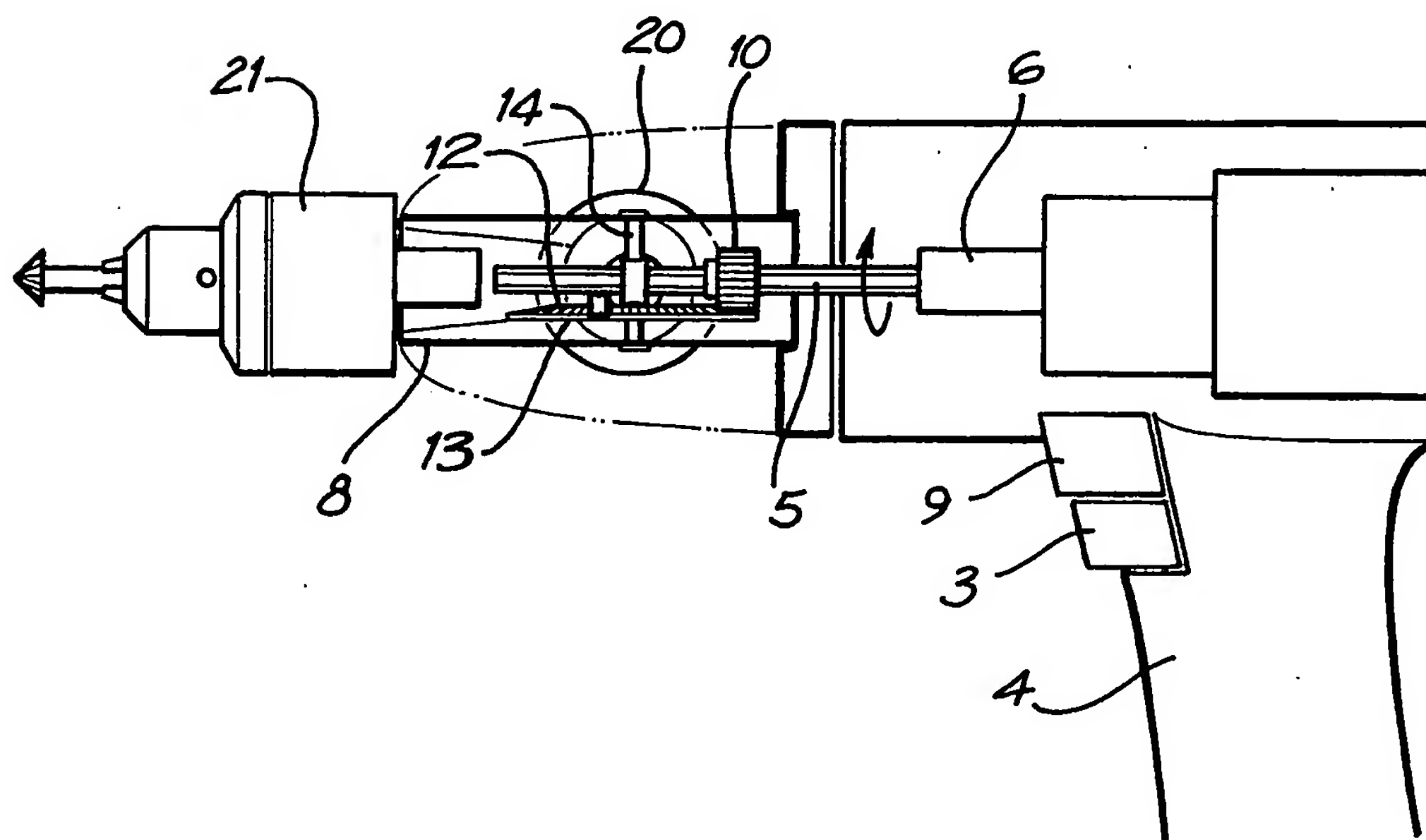


FIG. 6

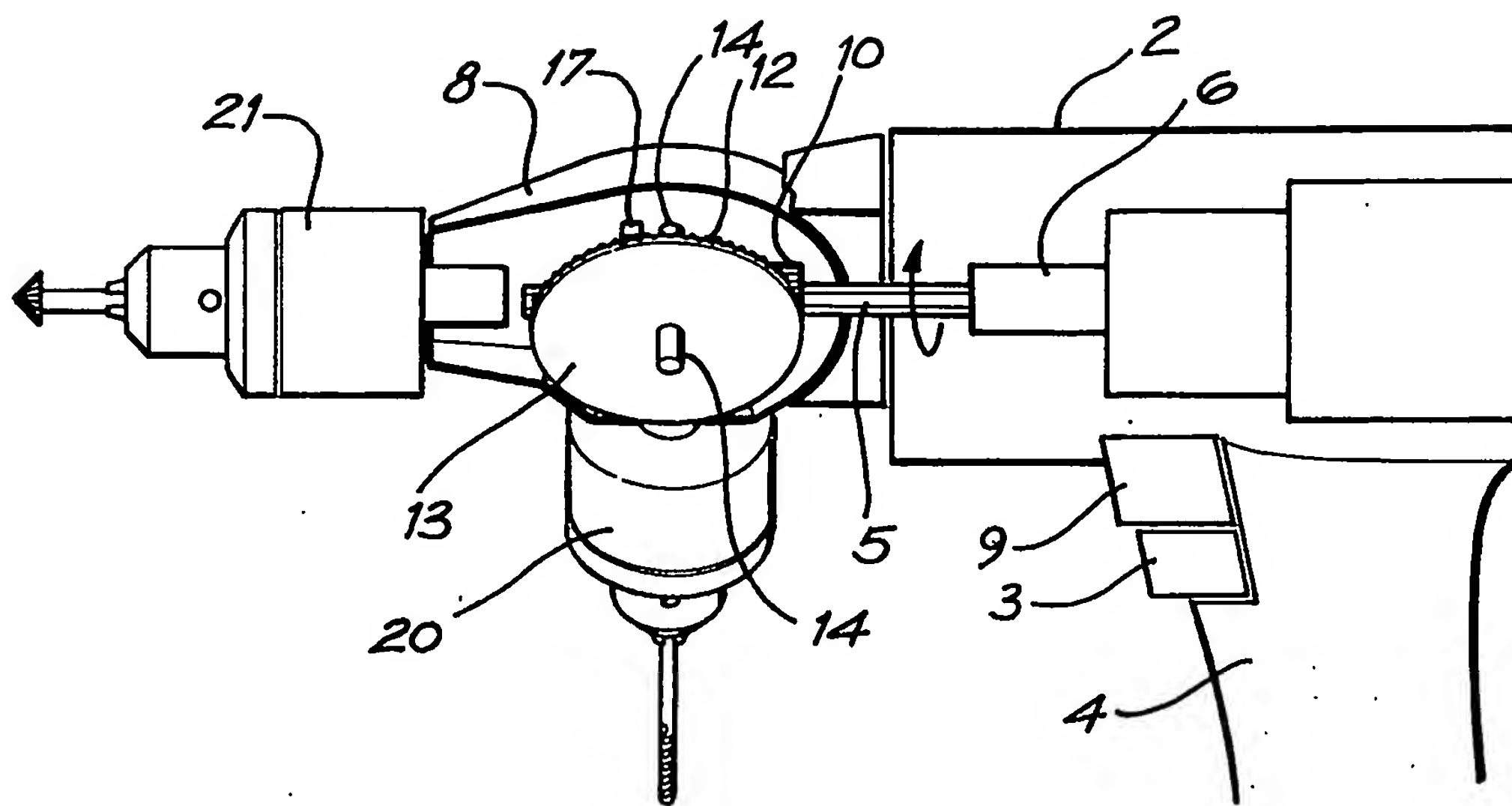


FIG. 7

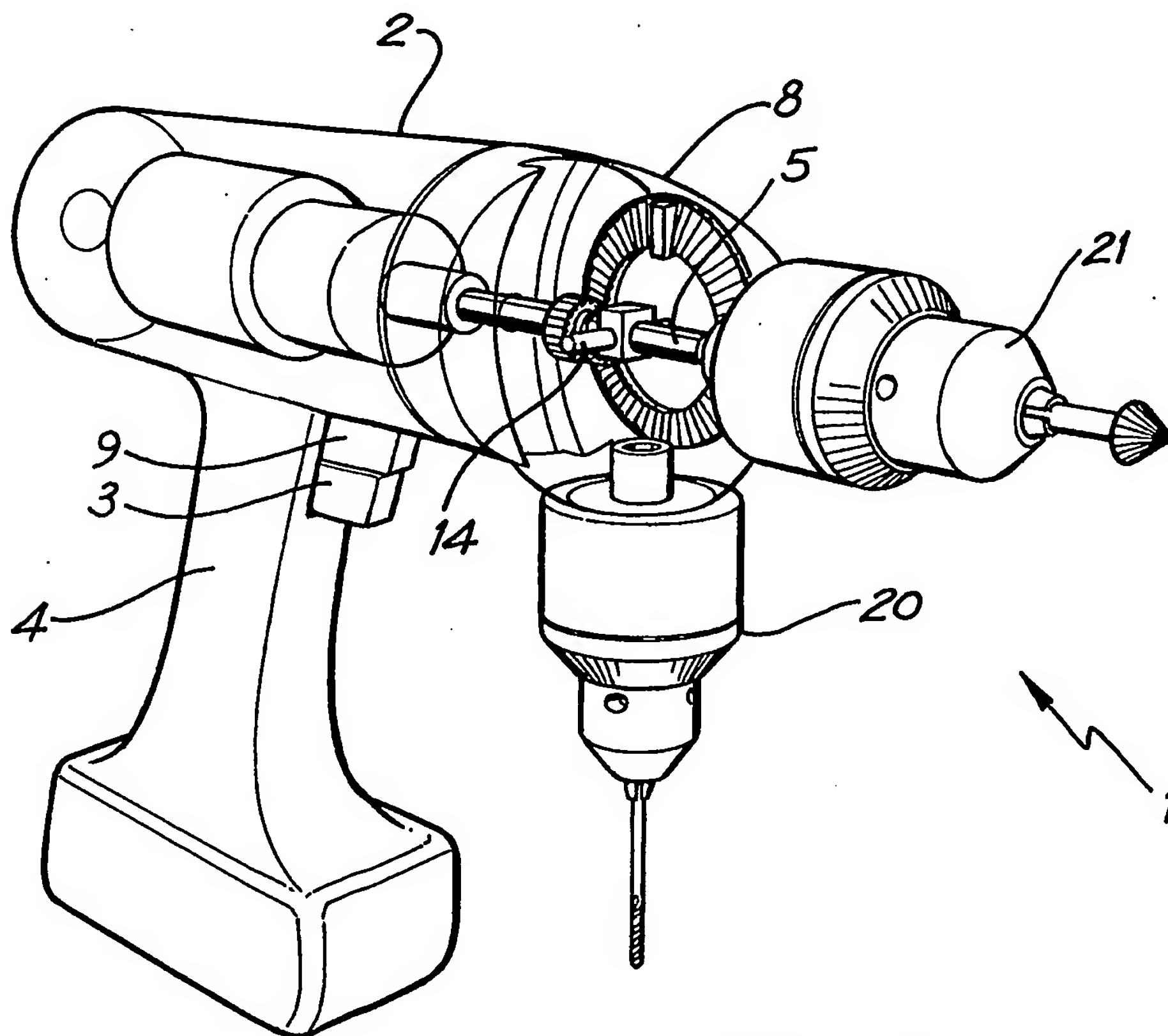
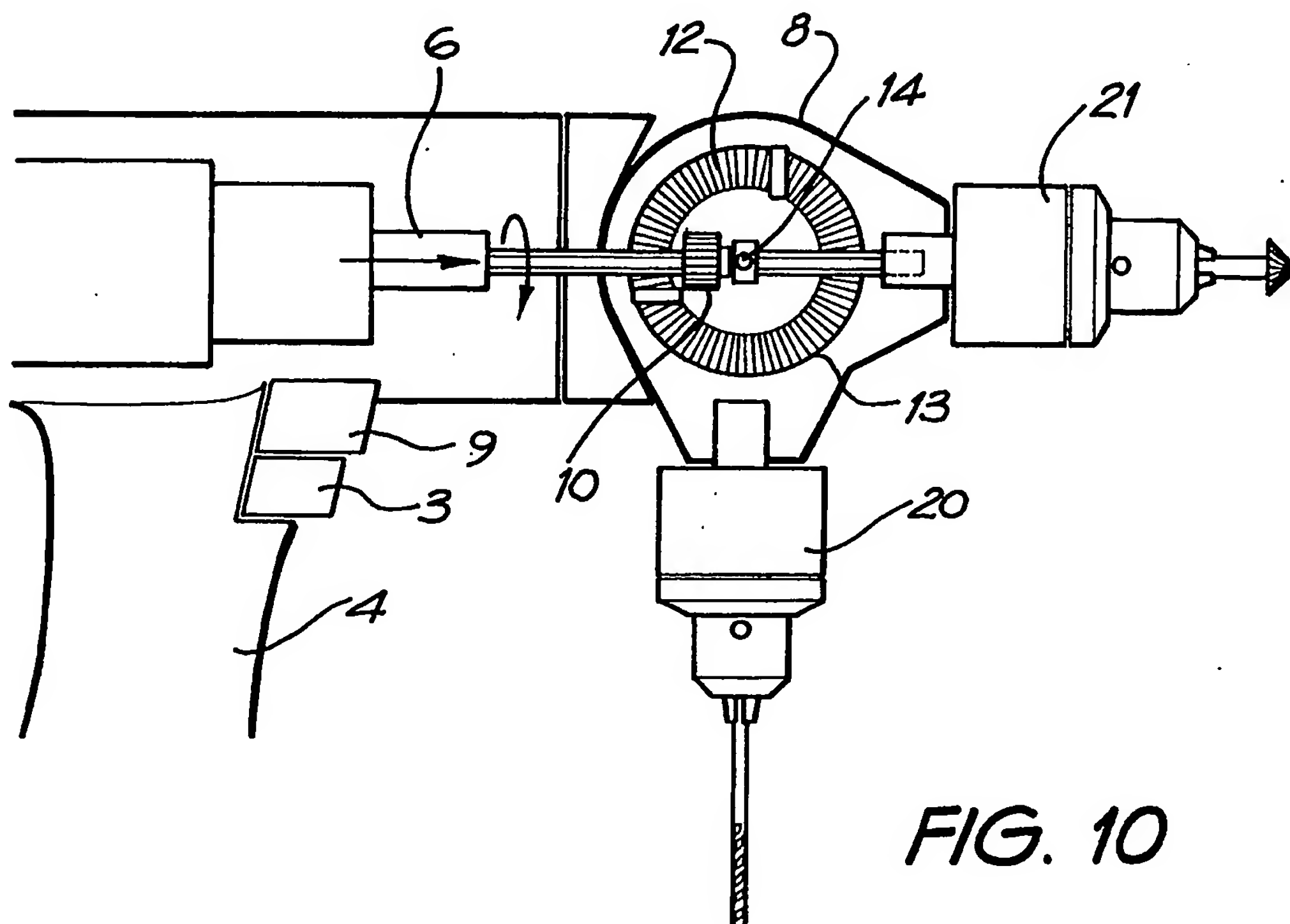
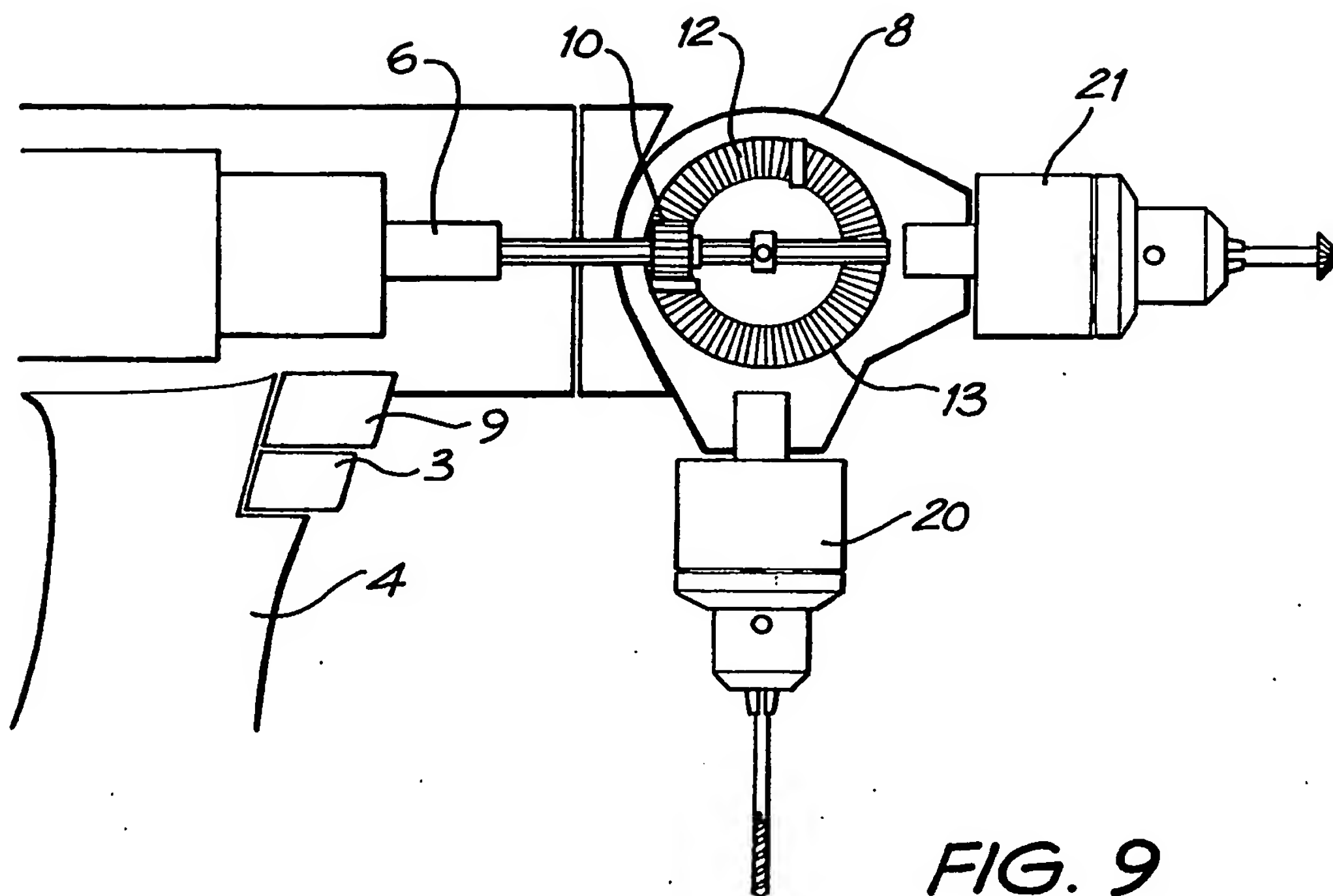


FIG. 8



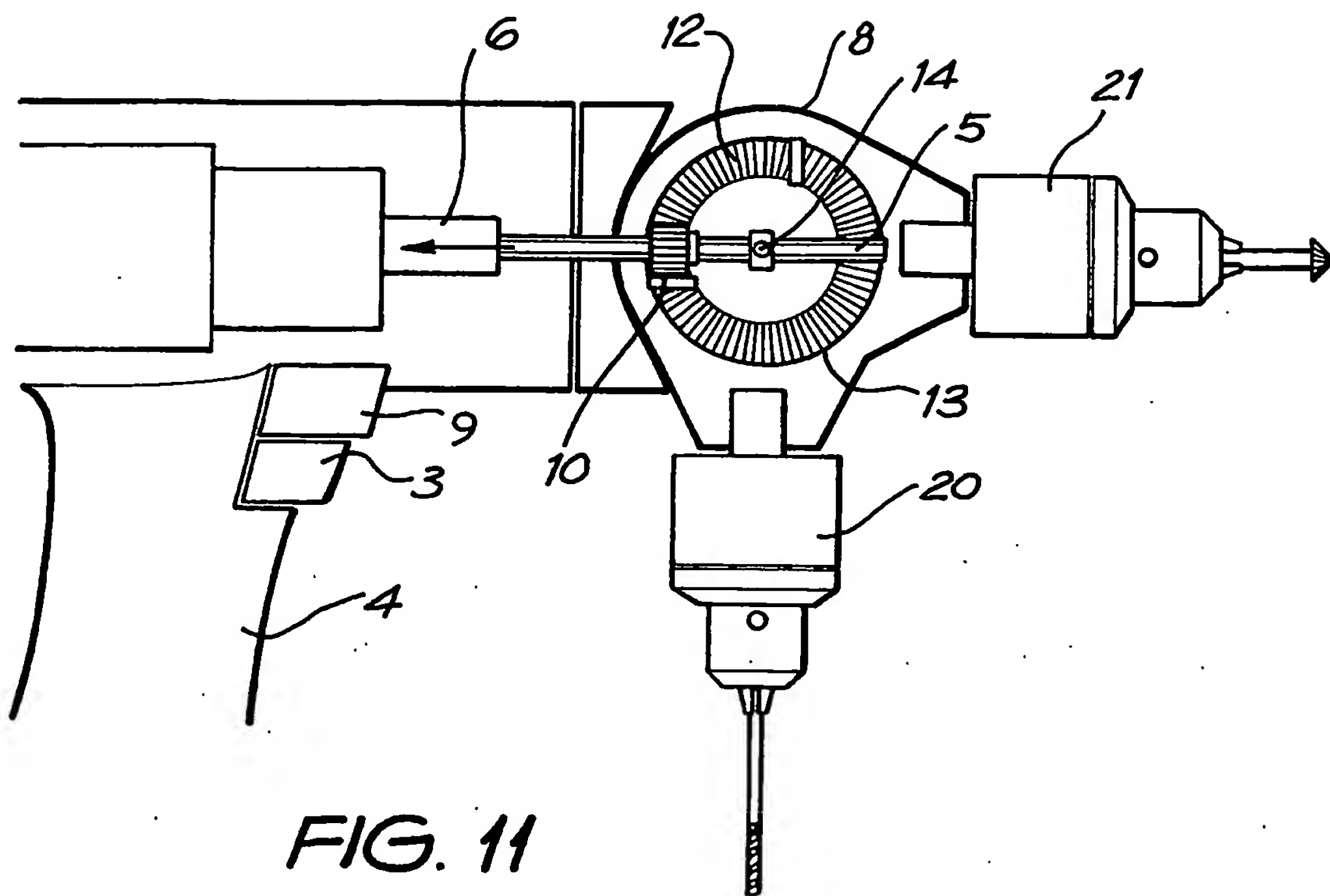


FIG. 11

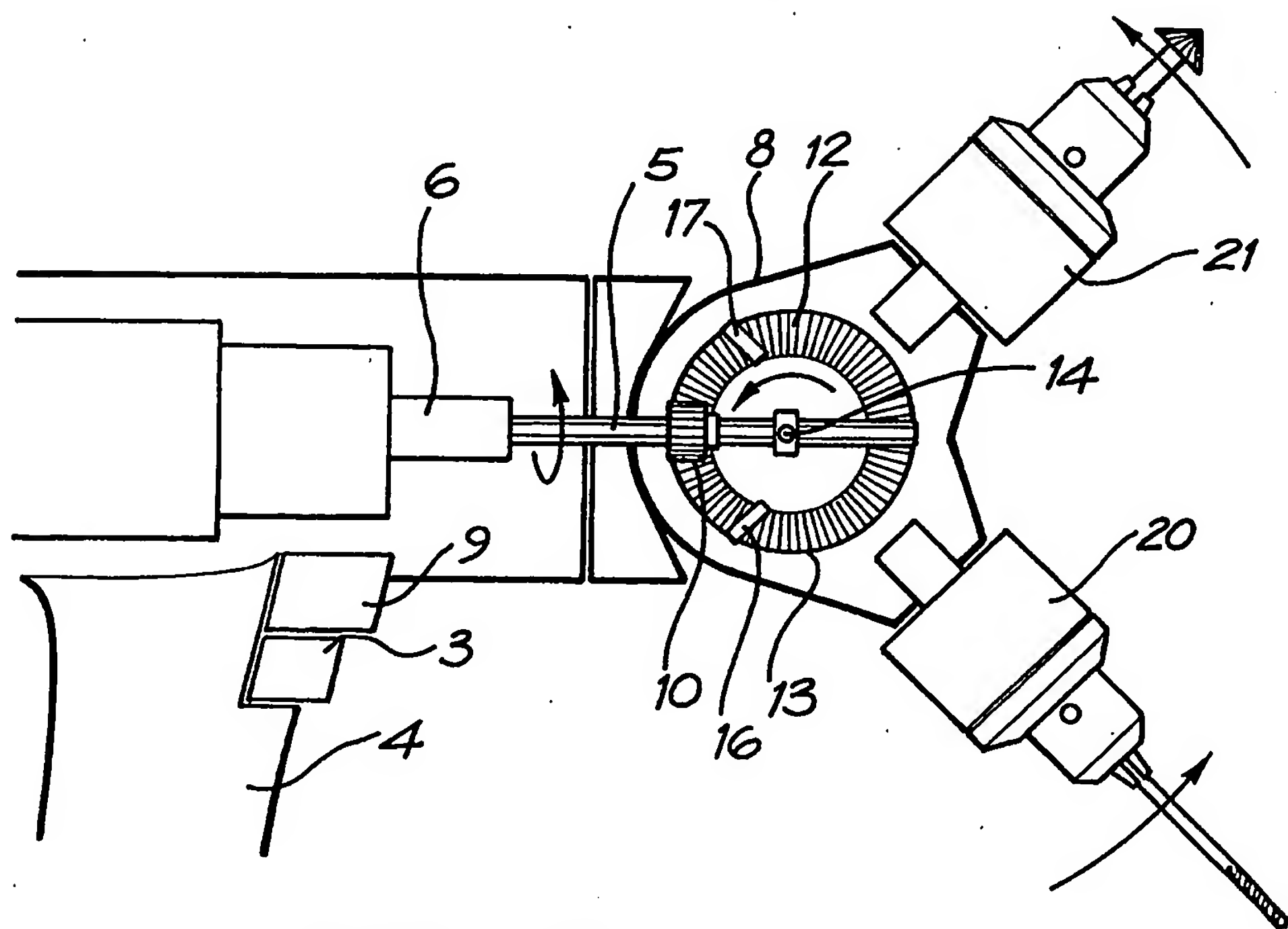


FIG. 12

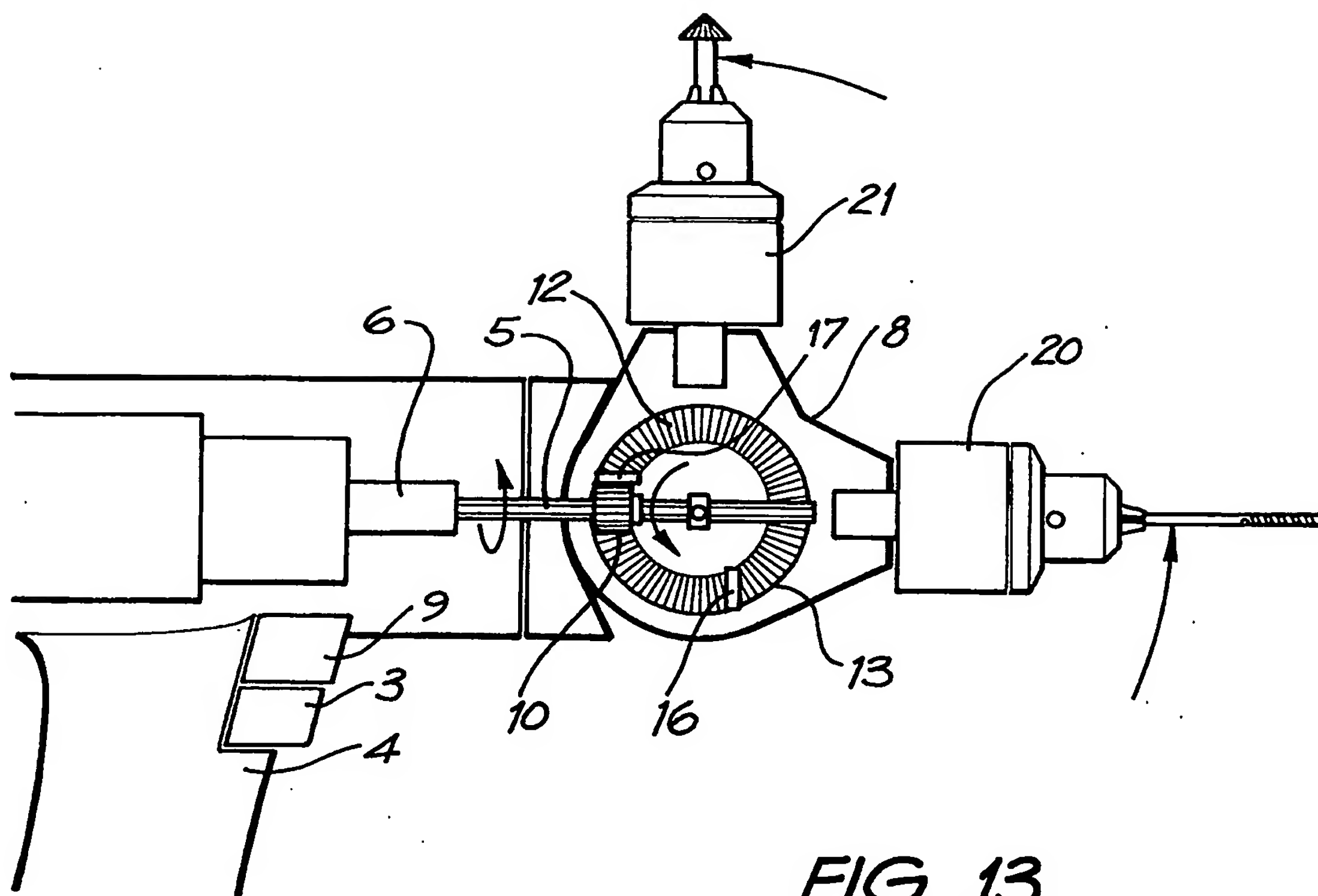


FIG. 13

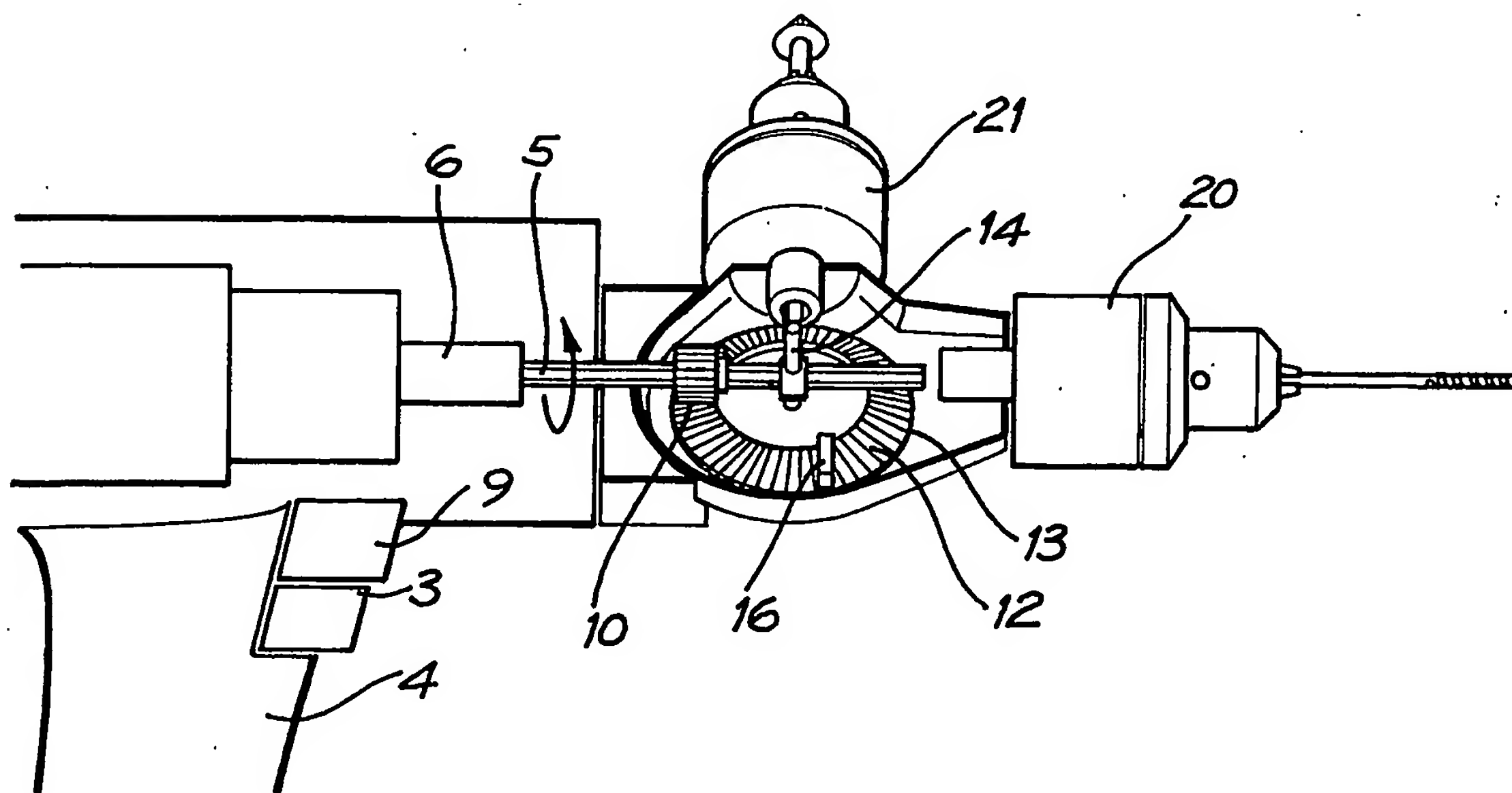


FIG. 14

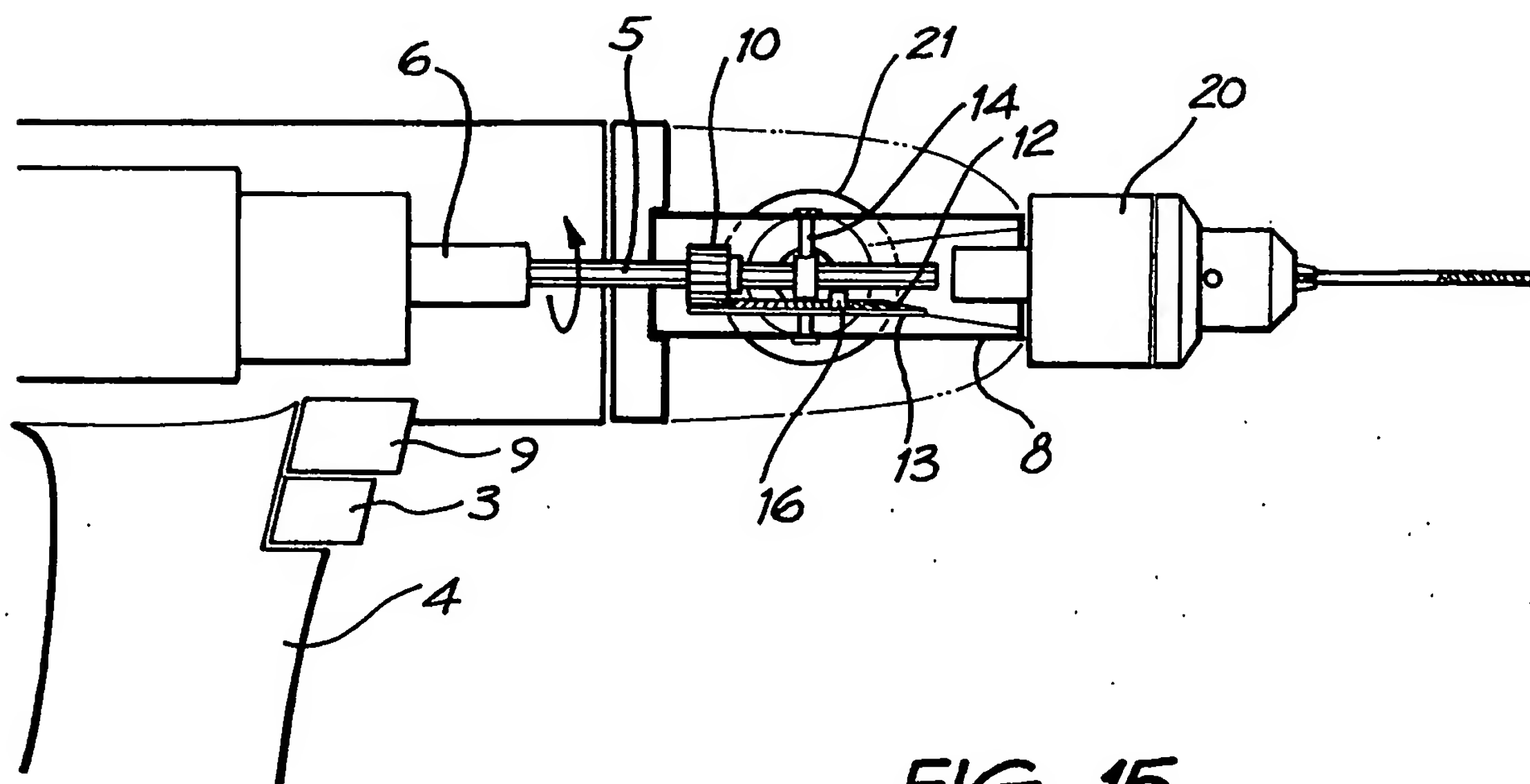


FIG. 15

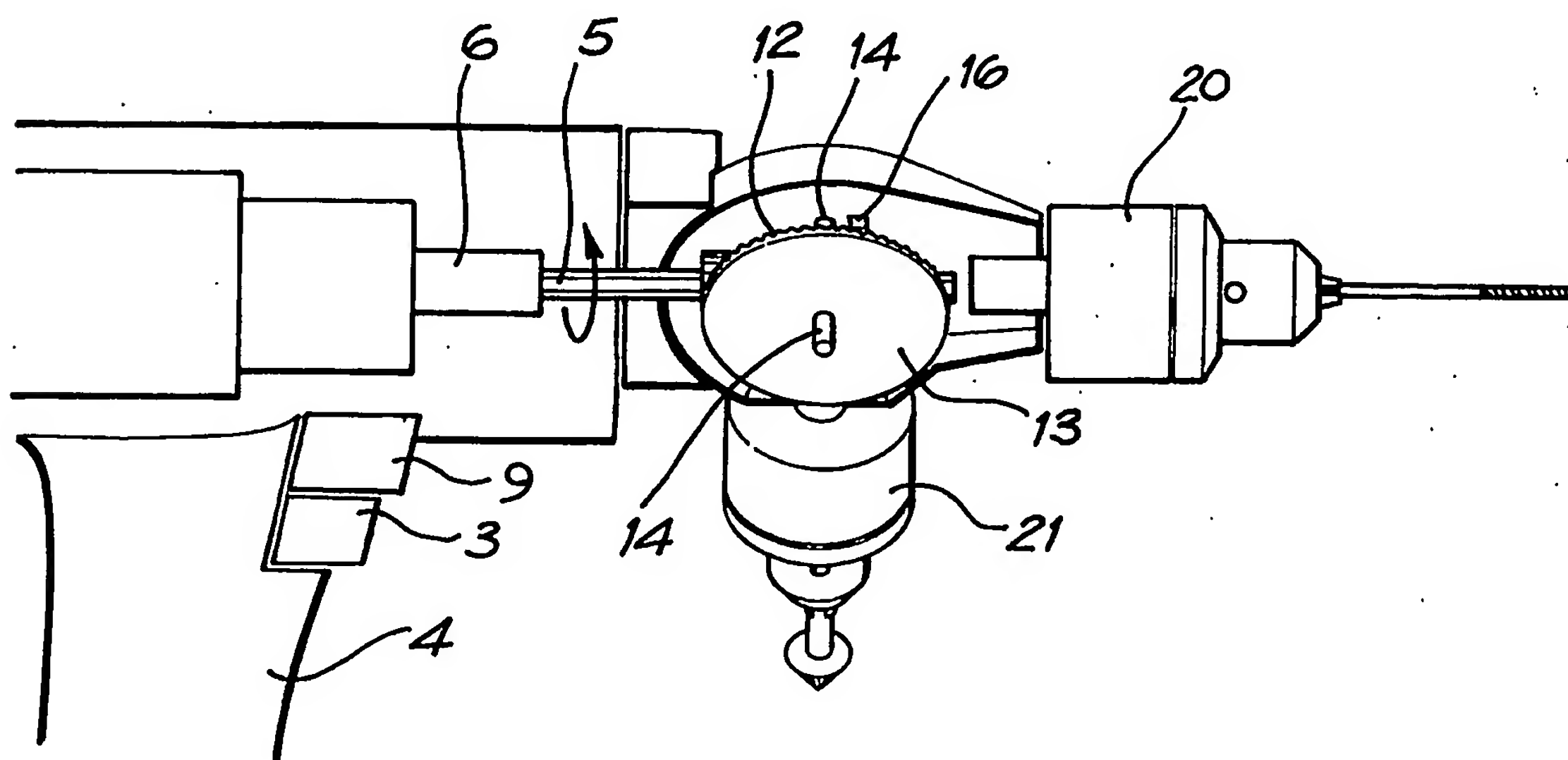


FIG. 16

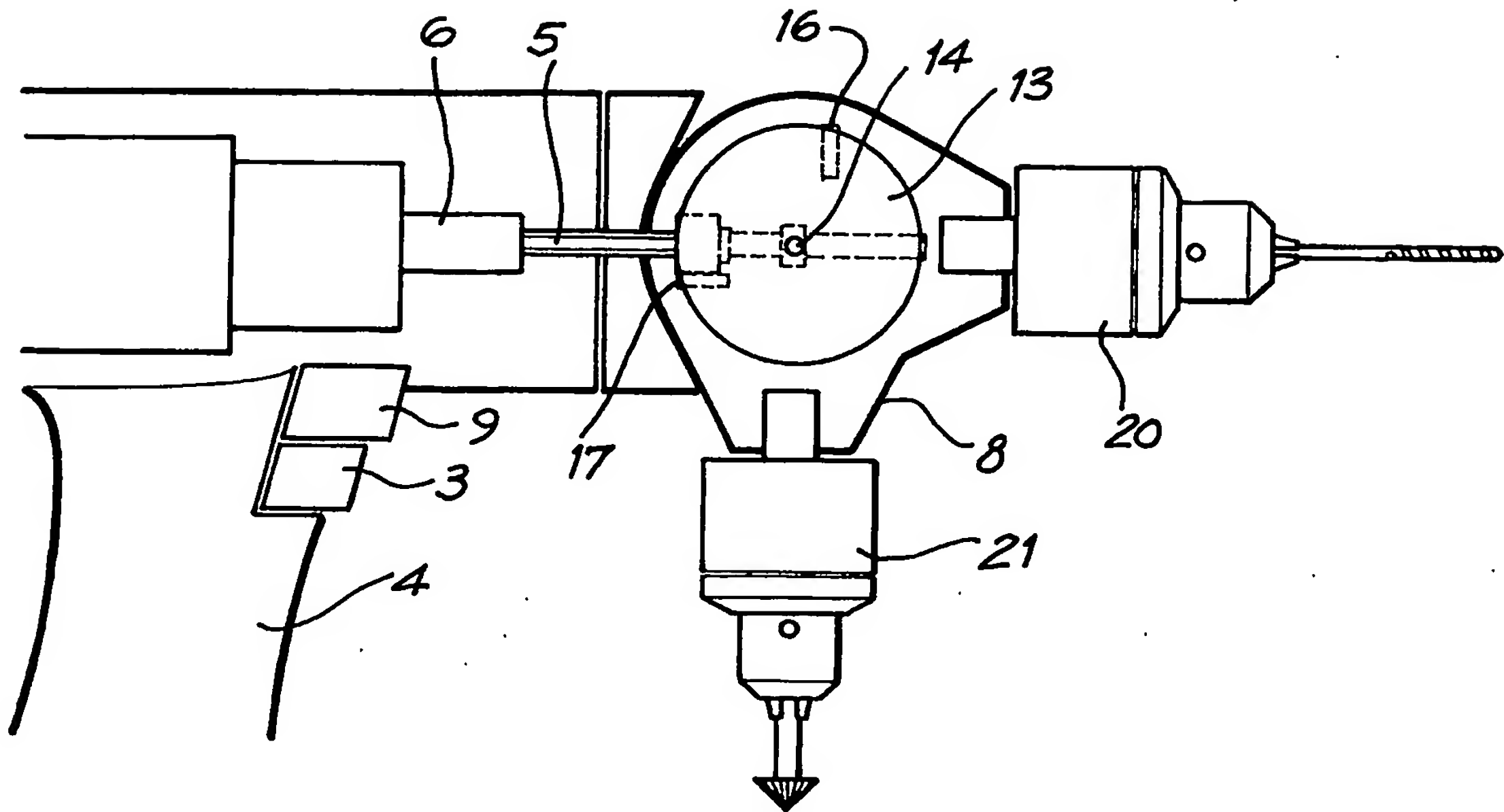


FIG. 17

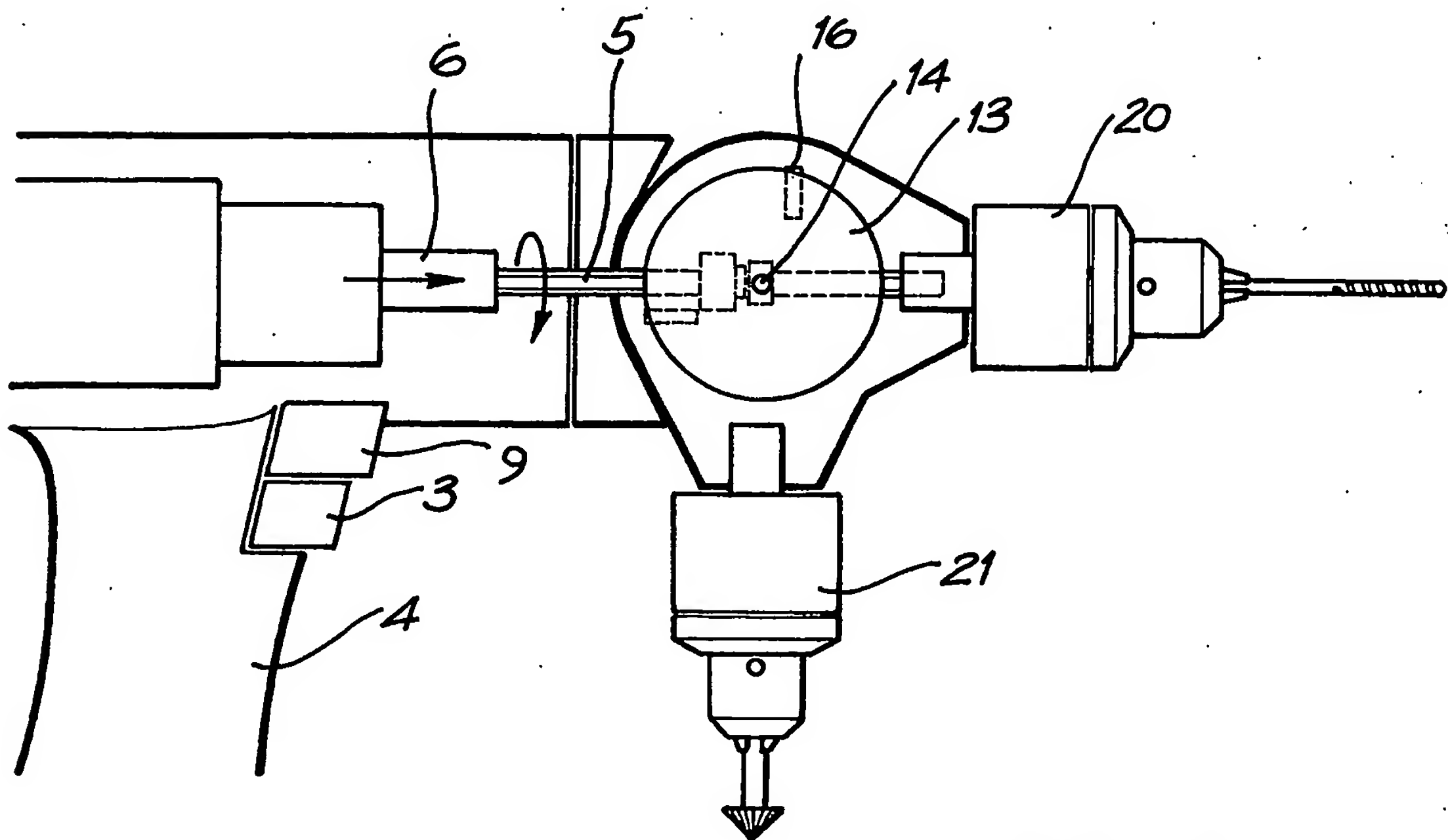


FIG. 18

INTERNATIONAL SEARCH REPORT

International application No.
PCT/AU2004/000360

A. CLASSIFICATION OF SUBJECT MATTER

Int. Cl. ⁷: B25F 1/02, 3/00 B25D 17/28

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)
WPAT, B25F/IC B23B 45/00, 45/02, 45/04 key words (SECOND+ or FURTHER+), CHUK+, (HAND DRILL),
(SECOND+, TWIN+, DOUBLE+, DUAL+, TWO, MULTIPLE+, FURTHER+

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	GB 2343646 A (MICHAEL BURVILL) 17 May 200 Whole document	1-4
A	EP 0673723 A (BLACK & DECKER INC) 27 September 1995 Whole document	1-4
A	DE 20205898 U (RUMPF W) 12 September 2002 Whole document	1-4

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* Special categories of cited documents:	
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"E" earlier application or patent but published on or after the international filing date	"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"O" document referring to an oral disclosure, use, exhibition or other means	"&" document member of the same patent family
"P" document published prior to the international filing date but later than the priority date claimed	

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16 APR 2004

Name and mailing address of the ISA/AU
AUSTRALIAN PATENT OFFICE
PO BOX 200, WODEN ACT 2606, AUSTRALIA
E-mail address: pct@ipaustalia.gov.au
Facsimile No. (02) 6285 3929

Authorized officer

SARAVANAMUTHU PONNAMPALAM
Telephone No : (02) 6283 2070

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.

PCT/AU2004/000360

This Annex lists the known "A" publication level patent family members relating to the patent documents cited in the above-mentioned international search report. The Australian Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent Document Cited in Search Report				Patent Family Member			
GB	2343646	AU	10665/00	WO	0029173		
EP	0673723	AU	15047/95	CA	2145116	CN	1125651
DE	20205898	NONE					
Due to data integration issues this family listing may not include 10 digit Australian applications filed since May 2001.							
END OF ANNEX							